



# Cross Member Multi-Station Assembly – Case Study

*Version 0.0.1, 2020-11-19*

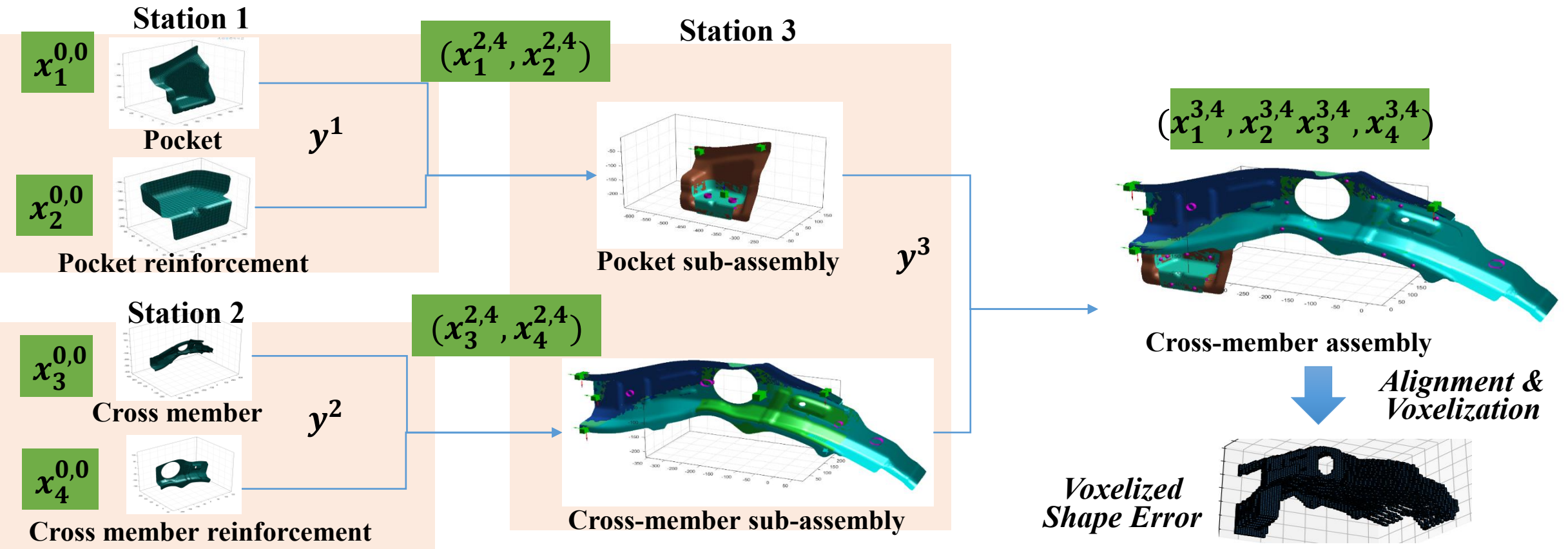
*Digital Lifecycle Management (DLM) Research Group*

*S. Sinha, P. Franciosa, D Ceglarek*

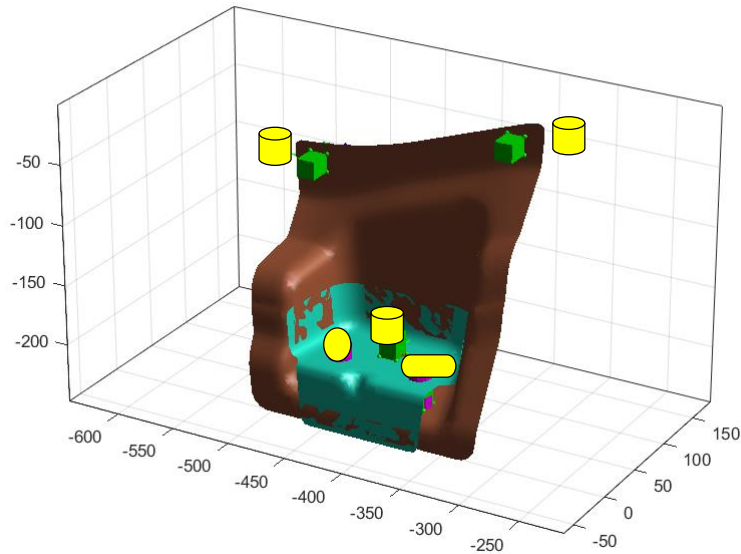
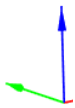
# Multi-Station Cross Member Assembly



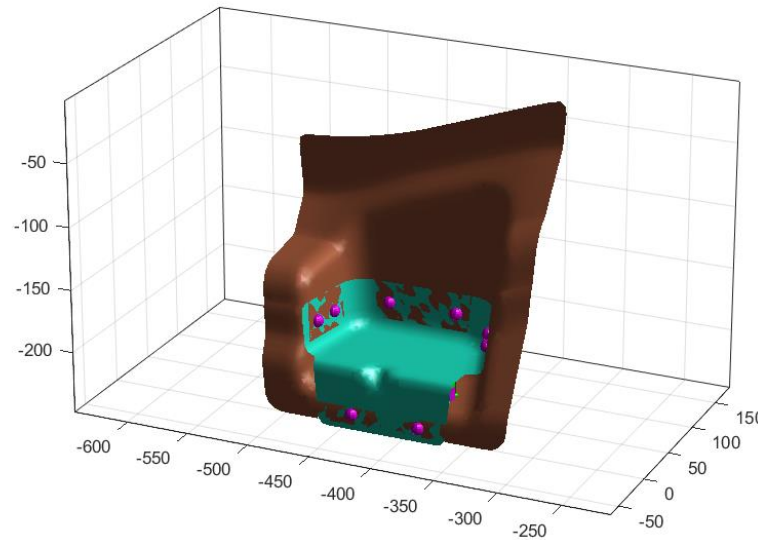
**4 part, 3 station cross-member assembly** is used for verification and validation of the model









Station 1: Pocket and Pocket Reinforcement Assembly



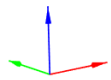
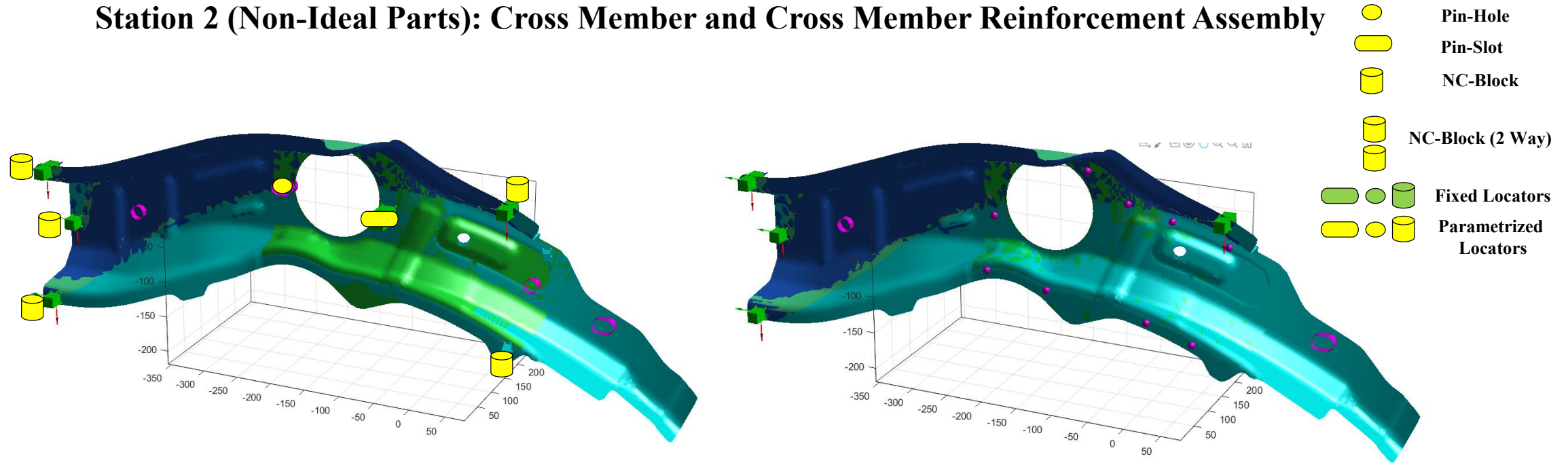
*Stage 1: Positioning , Stage 2: Clamping*



*Stage 3: Fastening , Stage 4: Release*

-  Pin-Hole
-  Pin-Slot
-  NC-Block
-  NC-Block (2 Way)
-  Fixed Locators
-  Parametrized Locators

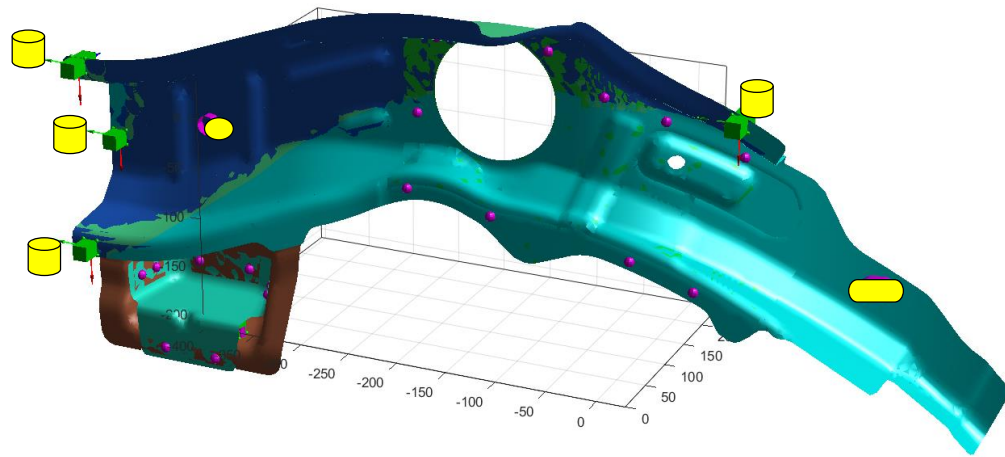
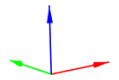
Station 2 (Non-Ideal Parts): Cross Member and Cross Member Reinforcement Assembly



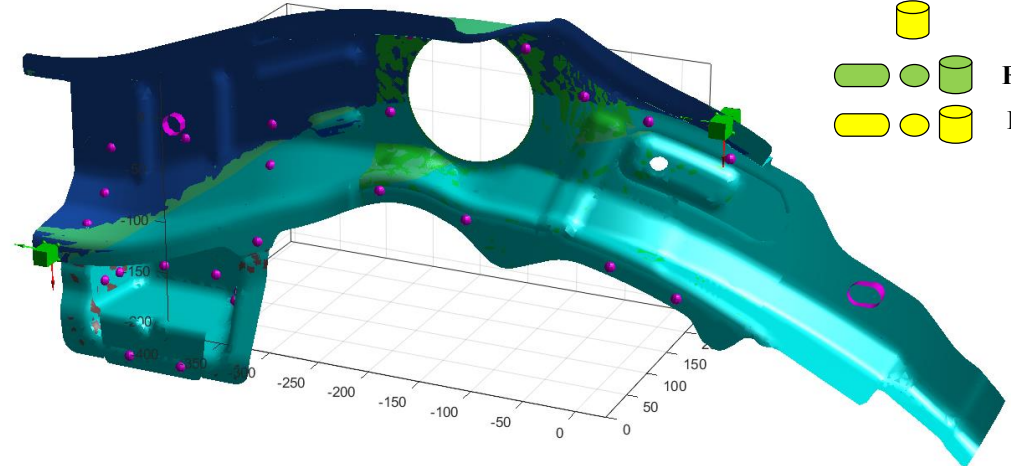
Stage 1: Positioning , Stage 2: Clamping

Stage 3: Fastening , Stage 4: Release







Station 3 (**Non-Ideal Parts**): Cross Member and Pocket Assembly



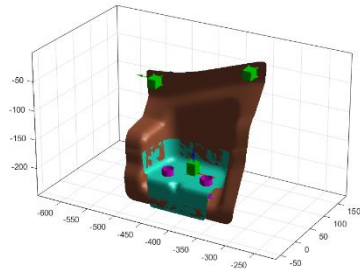
*Stage 1: Positioning , Stage 2: Clamping*



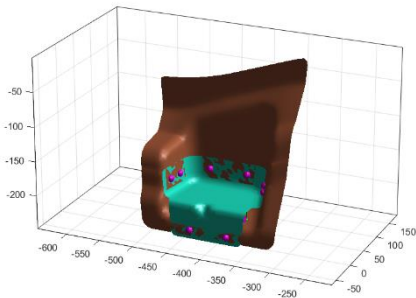
*Stage 3: Fastening , Stage 4: Release*

-  Pin-Hole
-  Pin-Slot
-  NC-Block
-  NC-Block (2 Way)
-  Fixed Locators
-  Parametrized Locators

Station 1: Pocket and Pocket Reinforcement Assembly – 48 Process Parameters



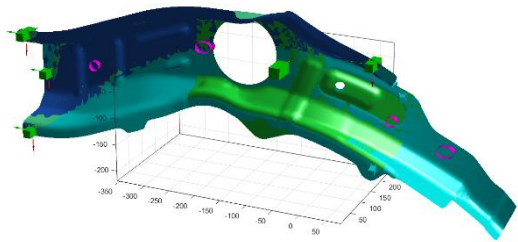
Stage 1: Positioning , Stage 2: Clamping



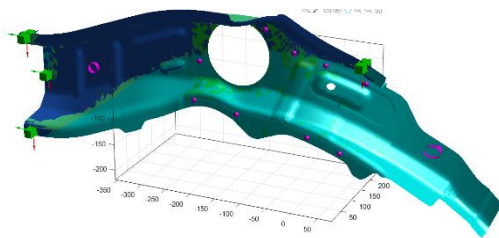
Stage 3: Fastening , Stage 4: Release

Stage ID	Process Parameter	# Process Param	Description
Non-Ideal (Stage 0)	Displacement of control point With large correlation length	1 Process Parameter	Part Variation (Part 1), Global effect
Non-Ideal (Stage 0)	Displacement of control point with a small correlation length	1 Process Parameter	Part Variation (Part 1), Local effect, Bending of flange
Non-Ideal (Stage 0)	Displacement of control point With large correlation length	1 Process Parameter	Part Variation (Part 2), Global effect
Non-Ideal (Stage 0)	Displacement of control point with a small correlation length	1 Process Parameter	Part Variation (Part 1), Local effect, Bending of flange
Positioning (Stage 1)	Pinhole, Pinhole	3 Process Parameters	Positioning (in plane movement)
Clamping (Stage 2)	Clamp (x,y and z) displacement	3*3=9 process parameters	Clamping
Fastening (Stage 3)	Tool Displacement in x,y and z direction	8*3=24 process parameters	Joining tool
Fastening (Stage 3)	Joint failure if Gap > threshold	8 binary variables for successful joints	Joining Tool


Station 2: Cross Member and Cross Member Reinforcement Assembly – 65 Process Parameters



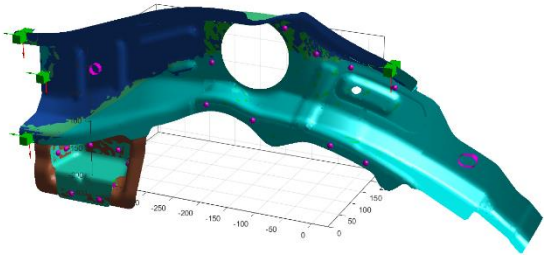
Stage 1: Positioning ,  
Stage 2: Clamping



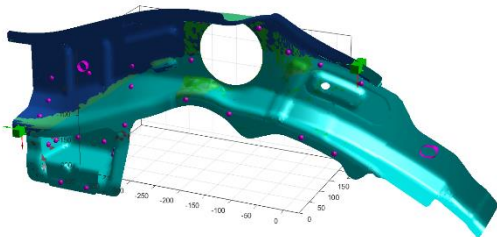
Stage 3: Fastening ,  
Stage 4: Release

Stage ID	Process Parameter		Description
Non-Ideal (Stage 0)	Displacement of control point With large correlation length	1 Process Parameter	Part Variation (Part 1), Global effect
Non-Ideal (Stage 0)	Displacement of control point with a small correlation length	1 Process Parameter	Part Variation (Part 1), Local effect, Bending of flange
Non-Ideal (Stage 0)	Displacement of control point With large correlation length	1 Process Parameter	Part Variation (Part 2), Global effect
Non-Ideal (Stage 0)	Displacement of control point with a small correlation length	1 Process Parameter	Part Variation (Part 2), Local effect, Bending of flange
Positioning (Stage 1)	Pin-Hole and Pin-slot	3 Process Parameters	Translation of pin hole and translation about pin-slot (rotation around pin hole)
Clamping (Stage 2)	x,y and z displacement of each clamp	<b>4*3=12 (Clamp S)</b> +2*3=6 (Clamp M) - 18	Clamping deviations of nominal
Fastening (Stage 3)	Tool Displacement in x,y and z direction	10*3=30 process parameters	Joining tool
Fastening (Stage 3)	Joint failure if Gap > threshold	10 binary variables for successful joints	

**Station 3: Cross Member and Pocket Assembly – 43 Process Parameters**



*Stage 1: Positioning , Stage 2: Clamping*

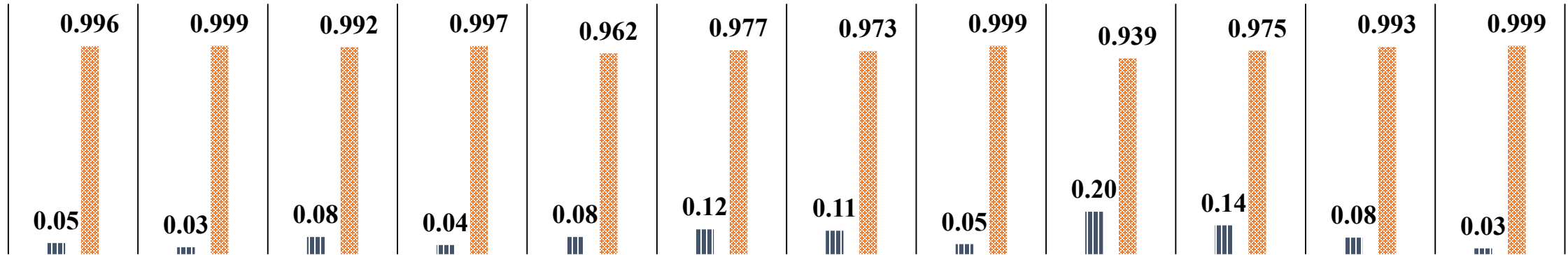


*Stage 3: Fastening , Stage 4: Release*

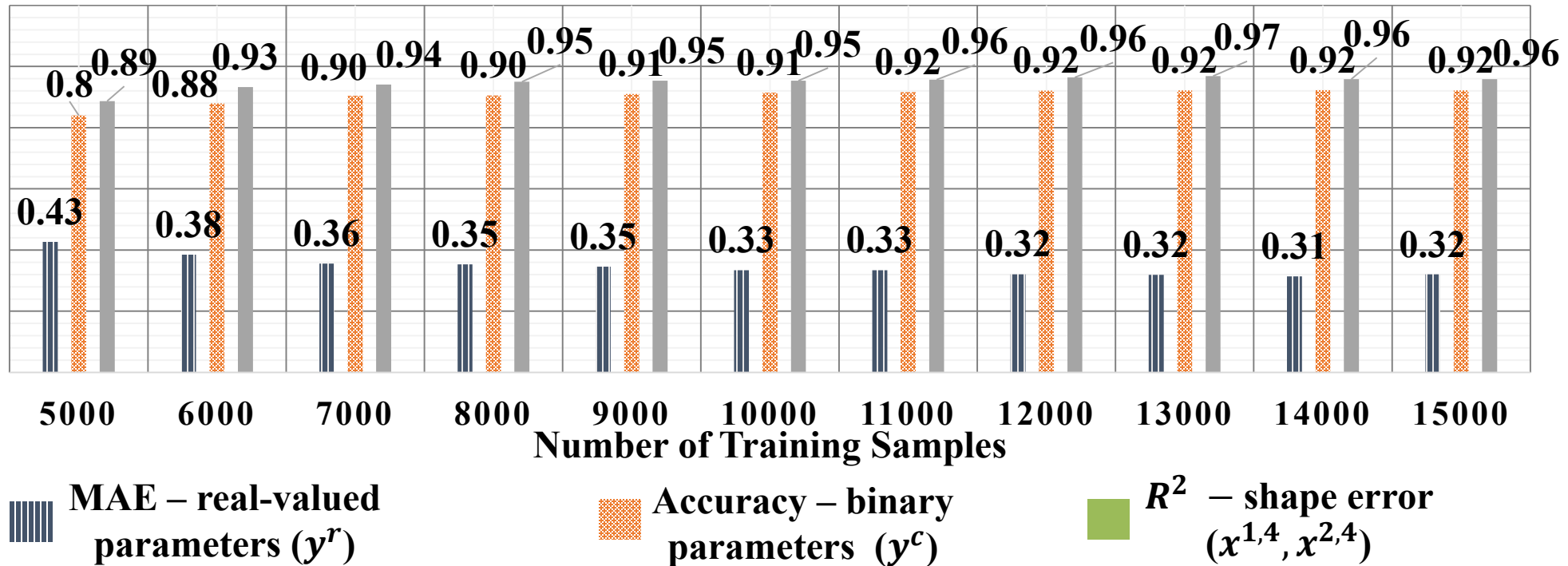
Stage ID	Process Parameter	# Process Params	Description
Positioning (Stage 1)	Pinhole, Pinslot	3 Process Parameters	Positioning (in plane movement)
Clamping (Stage 2)	Clamp (x,y and z) displacement	4*3=12 process parameters	Clamping
Fastening (Stage 3)	Tool Displacement in x,y and z direction	7*3=21 process parameters	Joining tool
	Joint failure if Gap > threshold	7 binary variables for successful joints	Joining Tool

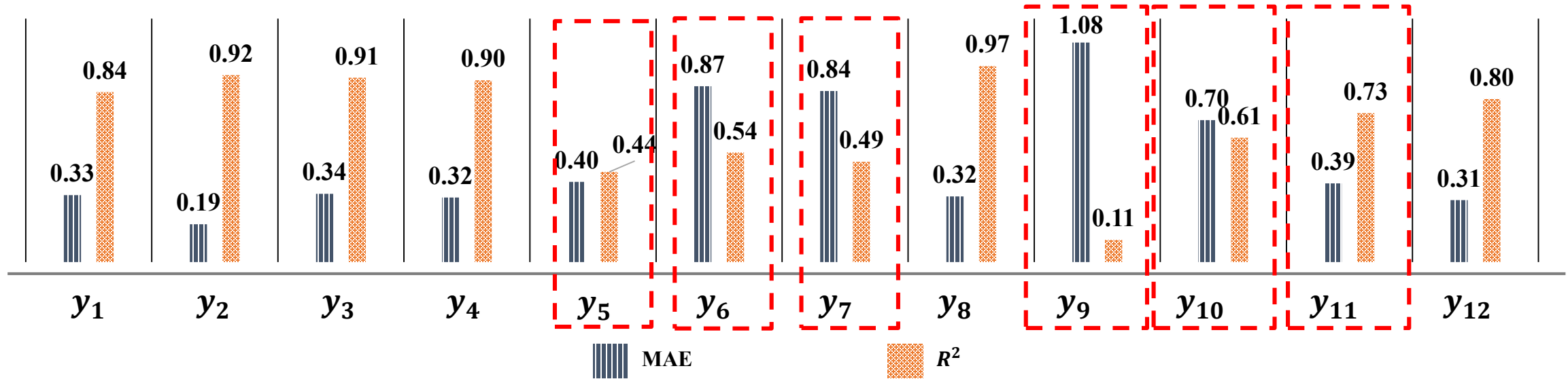
**Total: 158 Process Parameters**



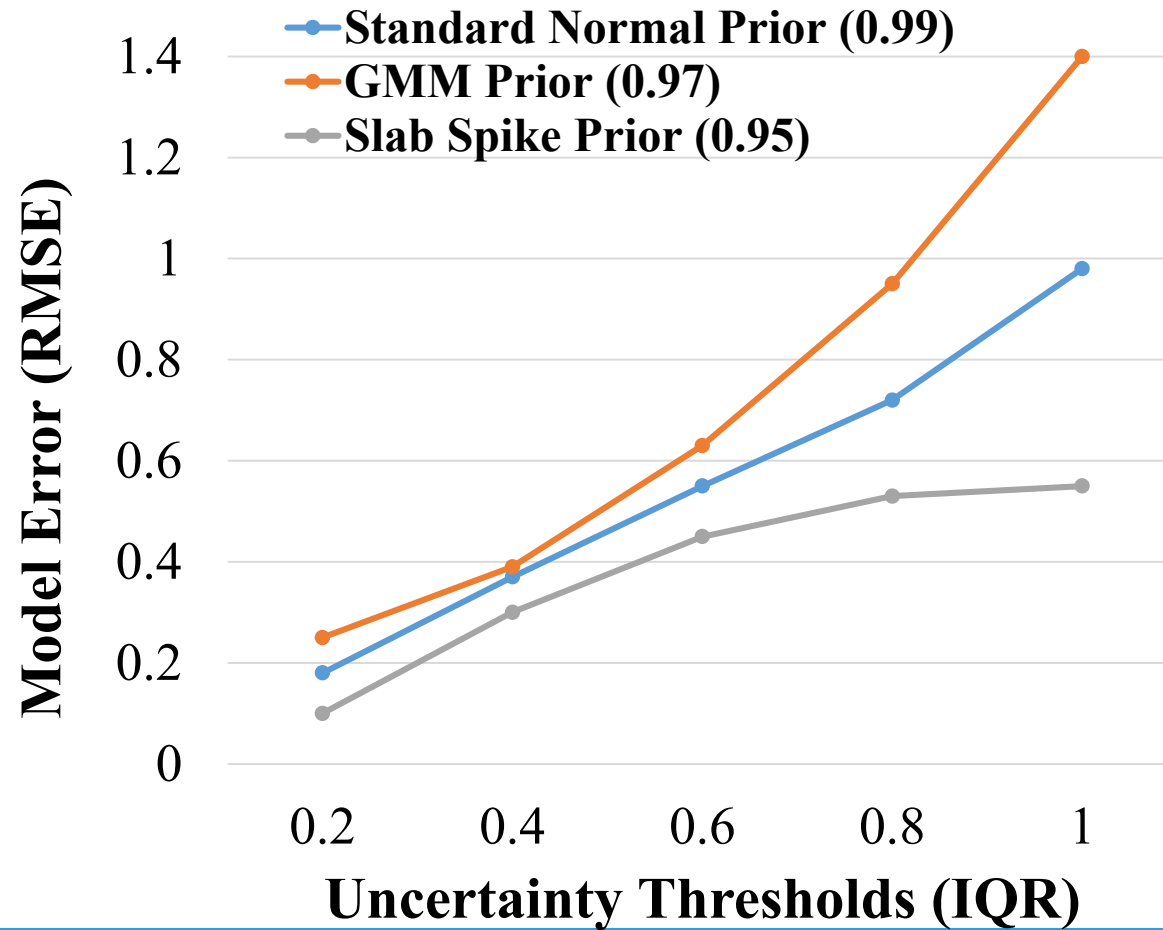


The Average **MAE** across all process parameters is **0.08 mm** and the **Average R<sup>2</sup>** is **98% at 100% Fault Multiplicity**





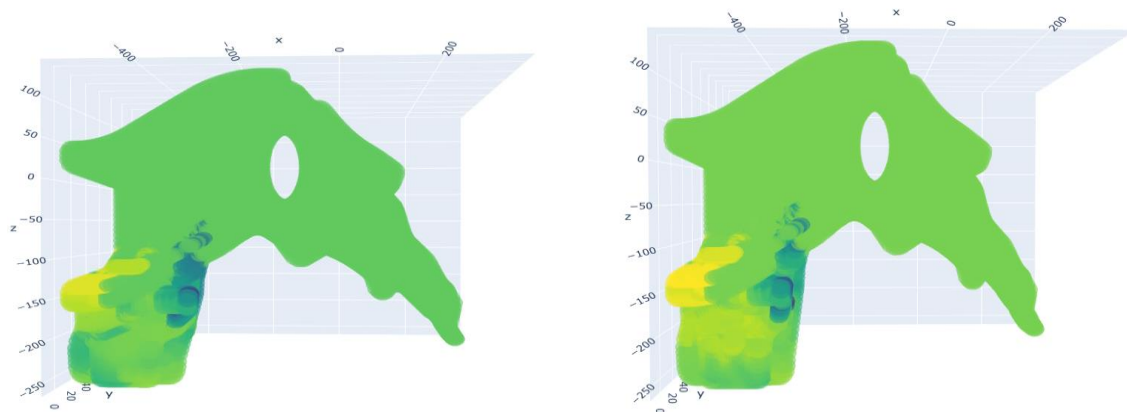
- Given the Multi-Station process the model Out-of-range performance capabilities are up to **70%**
- Given the non- continuous non- linearity of the process under different ranges of process parameters as compared to the continuous non-linearity of single stage assemblies
- This can be improved by adding training samples for a larger range
- The Extrapolation capabilities were up to **90%** in a single station assembly



# Results

The average **MAE** across all process parameters is **0.08 mm** and the **Average  $R^2$**  is **98%** at **100% Fault Multiplicity**

Object Shape Error Estimation accuracy for previous stages is at  **$RMSE = 0.0012$**  and  **$R^2 = 0.96$**

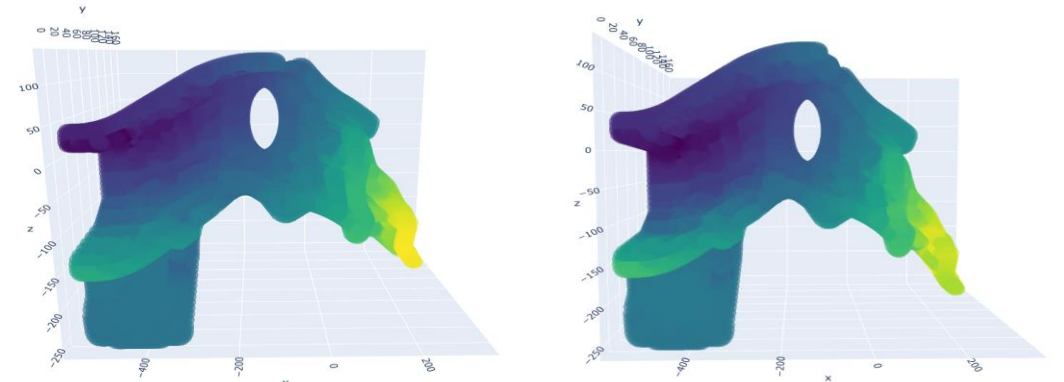


*Actual*

*Predicted*

*Station  $S_1$*

<b>MAE</b>	<b>0.0002 mm</b>
<b>RMSE</b>	<b>0.002 mm</b>
<b><math>R^2</math></b>	<b>0.97</b>
<b><math>R^2</math> Adjusted</b>	<b>0.97</b>



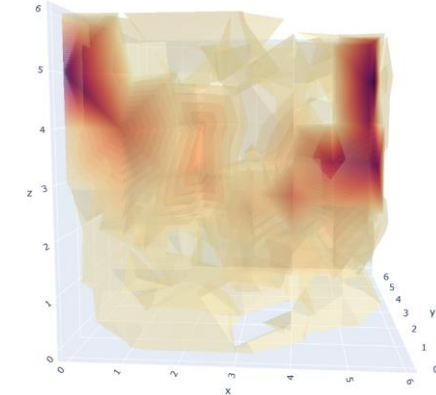
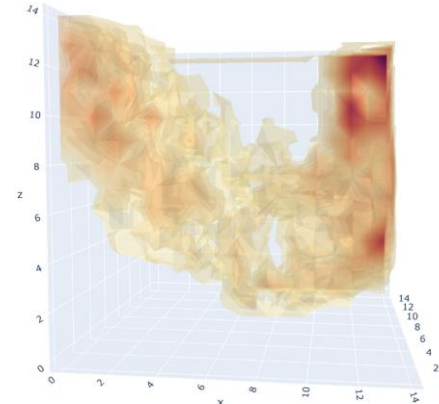
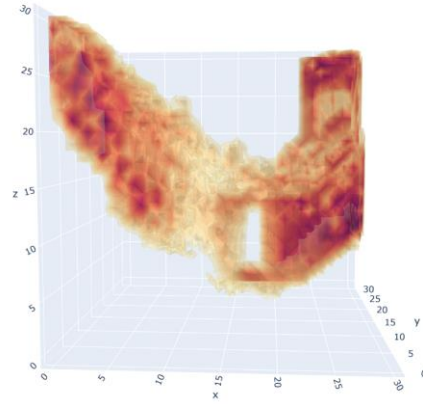
*Actual*

*Predicted*

*Station  $S_2$*

<b>MAE</b>	<b>0.0012 mm</b>
<b>RMSE</b>	<b>0.014 mm</b>
<b><math>R^2</math></b>	<b>0.96</b>
<b><math>R^2</math> Adjusted</b>	<b>0.96</b>

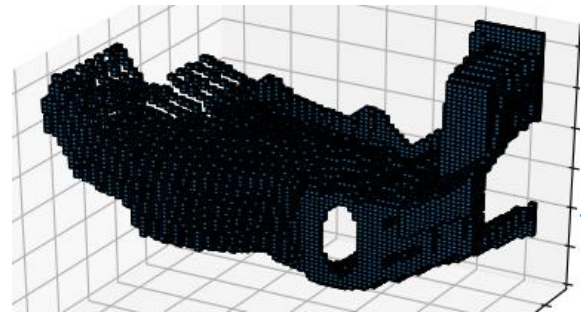
Feature Maps



Convolutional Block 1

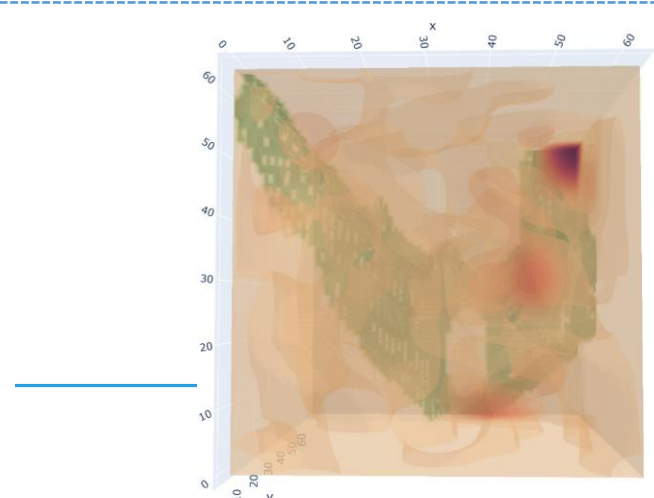
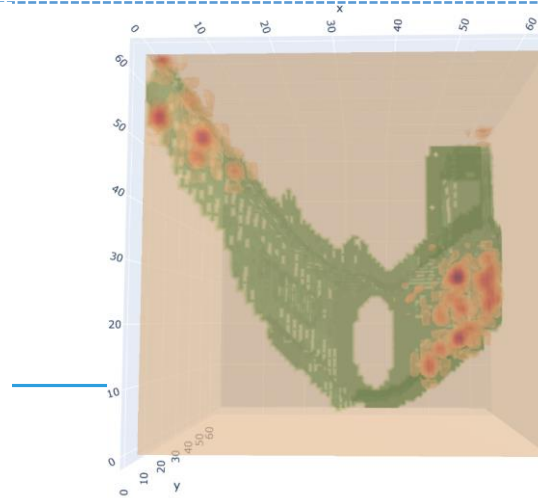
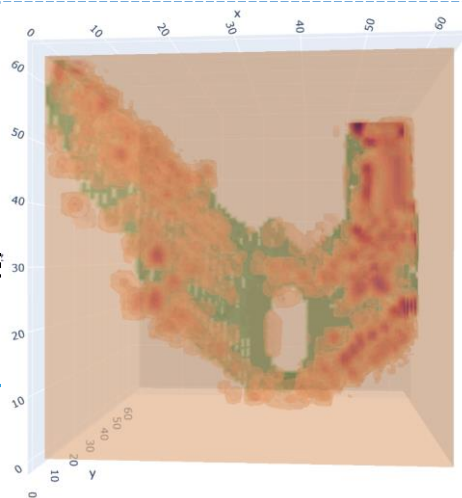
Convolutional Block 2

Convolutional Block 3



Voxelized Input

Network Gradients



$y_1 = 2$  (all other process parameters = 0)



# Thank-you

*Digital Lifecycle Management (DLM) Research Group*

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