



# In-Line Root Cause Analysis of Assembly Systems using Artificial Intelligence – Industrial Demonstration

*Digital Lifecycle Management (DLM) Research Group*

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*S. Sinha, E. Glorieux, M. Babu, P. Franciosa, D Ceglarek*

Industry challenge:

- *In-line root cause analysis* of defects using 3D surface scanners.



Approach

Integrate the knowledge of first engineering principle based Digital Twins and Big Data provided by high dimensional Measurement Systems using Artificial Intelligence to Diagnose Assembly Systems



Case study: 3D-Optical Robotic Scanner

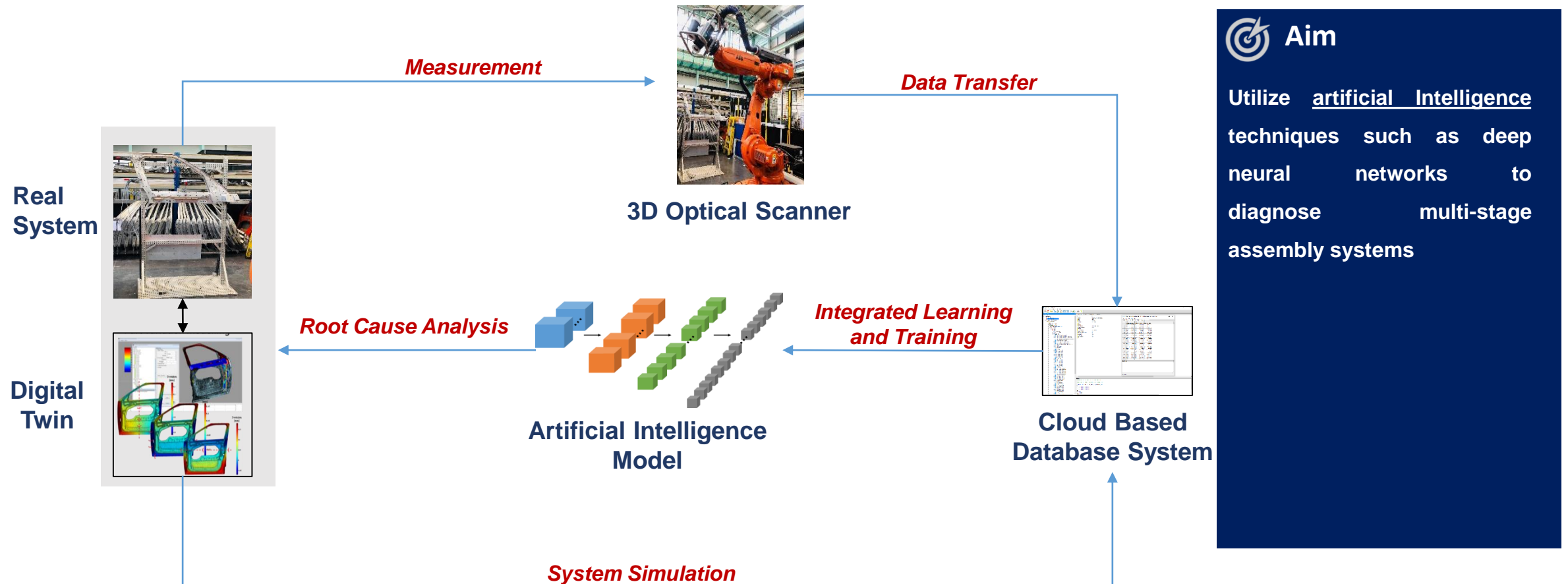


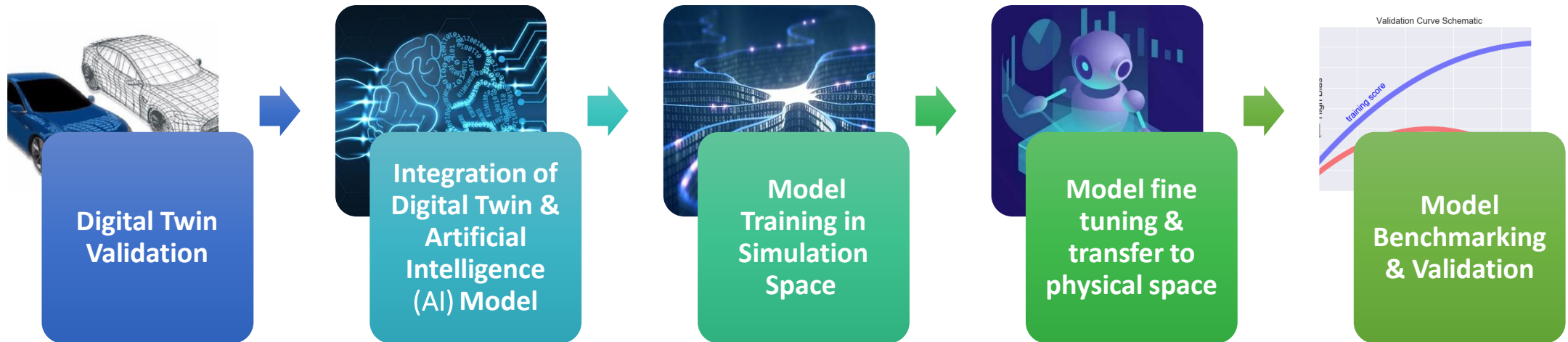
Key Benefits

- Increased productivity due to rapid fault diagnosis based on artificial intelligence models
- Continuous quality improvement due to on-line learning and training
- Reduction of dependence on hit and trial based manual expertise

# DIGITAL LIFECYCLE MANAGEMENT (DLM)

## SYSTEM SETUP



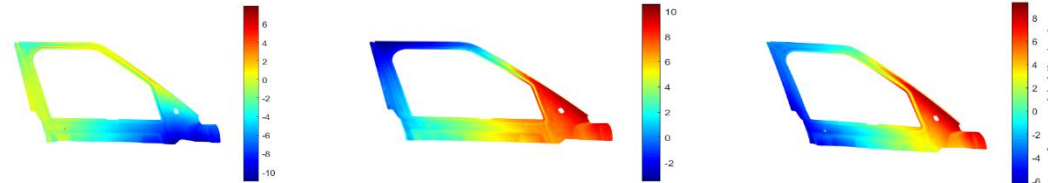


Index	Clamp_1	Clamp_2	Clamp_3	Clamp_4	Correlation Between Digital Twin and Actual System
1	0	0	0	0	1
2	-5	0	0	0	0.89
3	5	0	0	0	0.89
4	0	-5	0	0	0.92
5	0	5	0	0	0.88
6	0	0	-5	0	0.97
7	0	0	5	0	0.98
8	0	0	0	-5	0.97
9	0	0	0	5	0.99

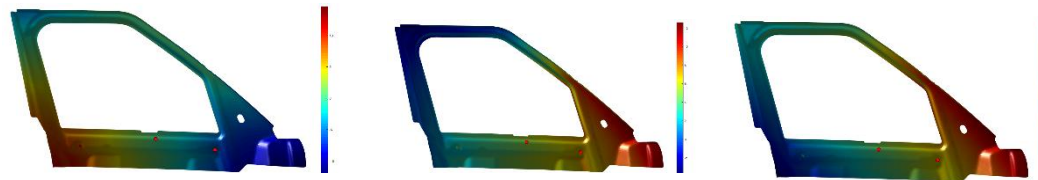
Experiments were conducted between data obtained from the surface scanner and data simulated from the digital twin

After correcting for rigid rotation due alignment, compensating for non-ideal part nature and fine tuning digital twin parameters the correlations were calculated

Actual System Data



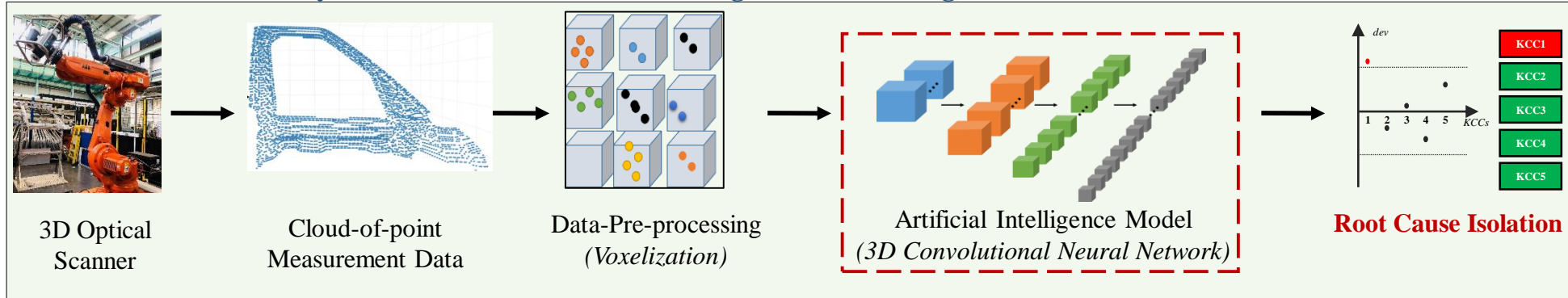
Digital Twin Data



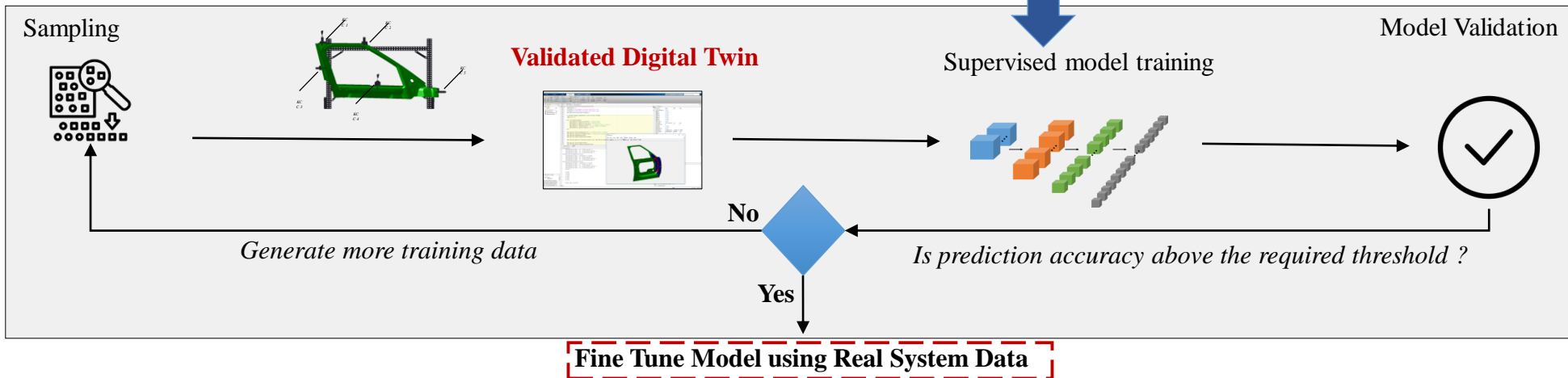
# DIGITAL LIFECYCLE MANAGEMENT (DLM)

# INTEGRATION OF DIGITAL TWIN & ARTIFICIAL INTELLIGENCE MODEL

## In-line Root Cause Analysis (After off-line model training and Fine tuning)

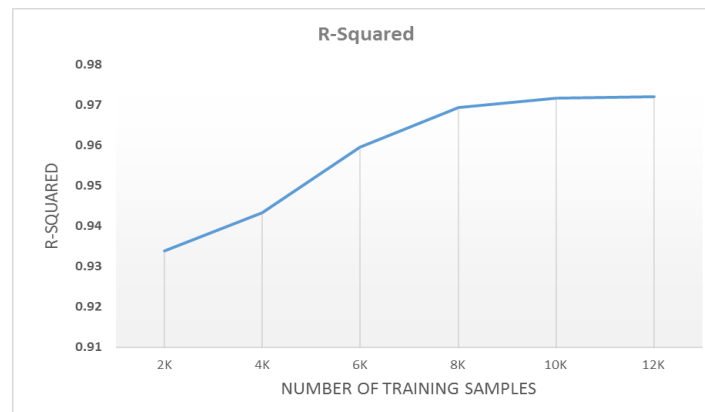
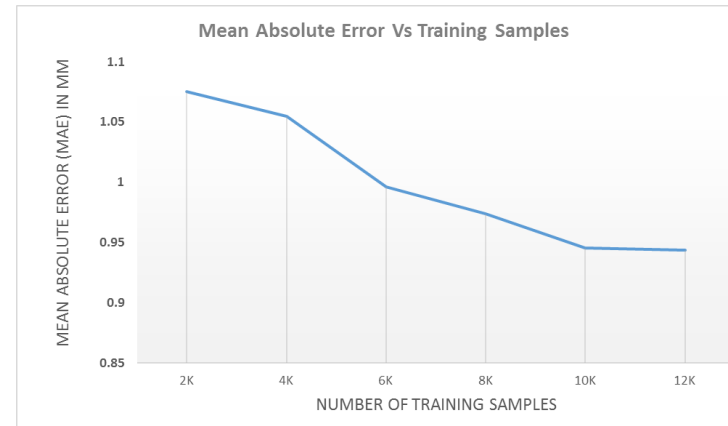
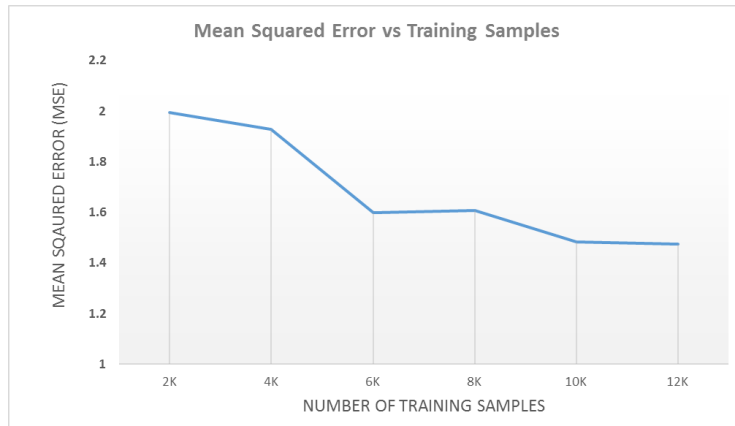


## Model Training (Off-line)



The 3D Convolutional Neural Network Model is trained using data generated from the validated digital twin until the required accuracy is obtained. The trained model is fine tuned using actual data obtained from the system to compensate for the difference between simulation and actual systems





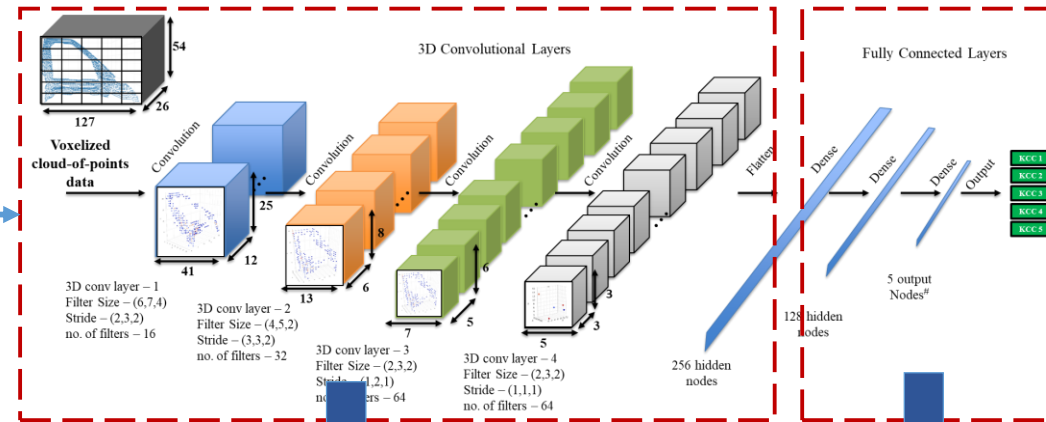
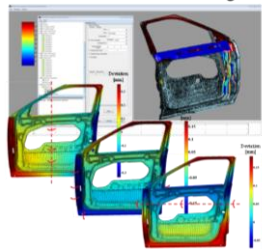
The model converges after 10K training samples in terms of error metrics such as Mean Absolute Error (MAE) and Mean Squared Error (MSE) as well as Goodness of fit determined by R-Squared Value (R<sup>2</sup>)



Labelled actual system data

The model is fine-tuned using the concept of transfer learning by freezing the weights of the convolutional layers and updating tuning the fully connected layers using a small sample of real data (~ 30 to 90 samples), this has significant improvement in model performance in the actual system

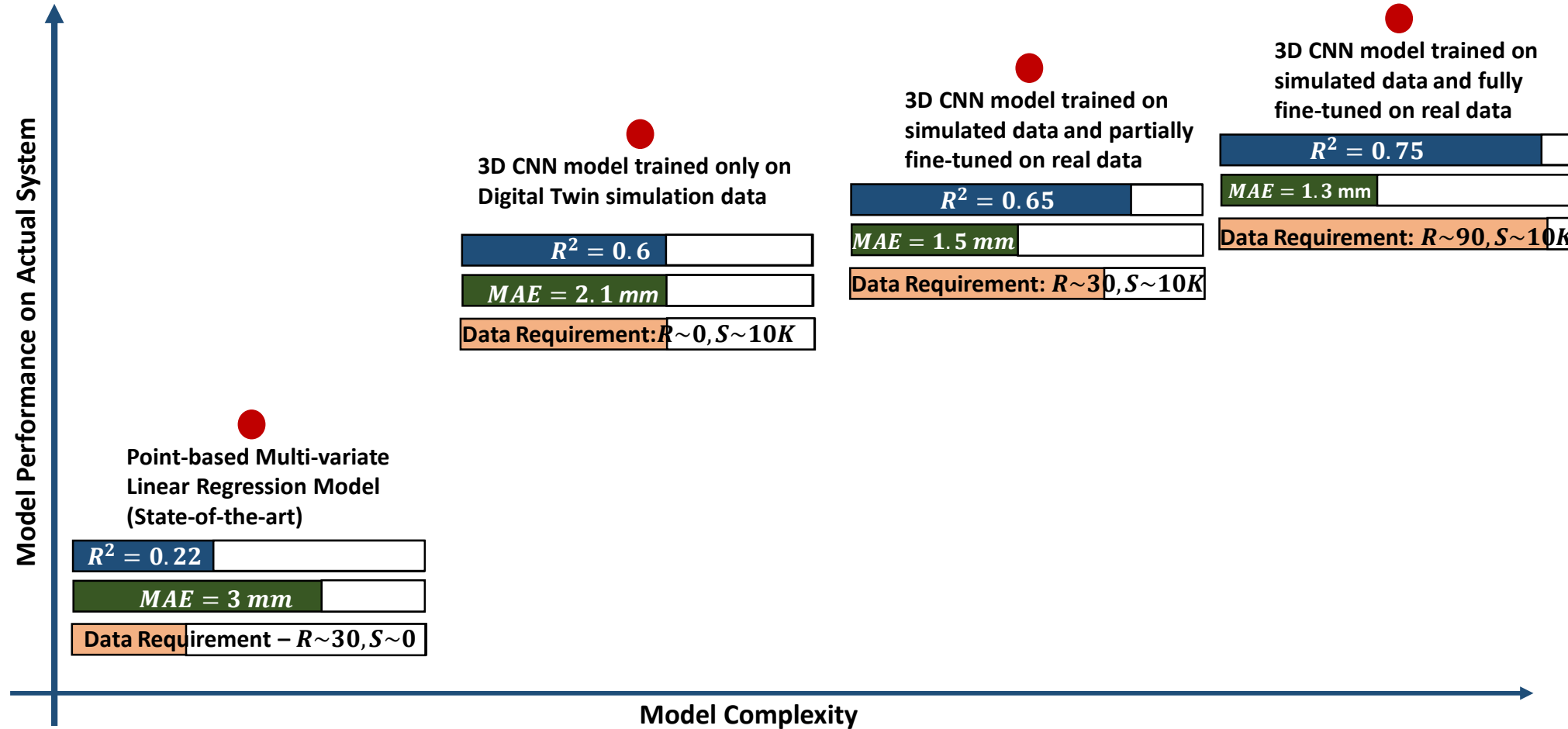
Model Trained and validated by Digital twin data



Freeze the initial convolutional layers as they are feature extractors already trained on large Digital Twin data

Fine Tune fully connected layers based on small sample of actual system data





## Benefits

- Enables to use a single model from design phase to full scale production phase by integrating small amount of actual system data obtained during operation
- Can be adapted to dynamic changes in the manufacturing system

NAME	TECHNIQUE	PURPOSE	VIEWPOINTS VS SCANNING
<a href="#">WLS400a (Hexagon)</a>	Stereovision	Dimensional quality	Viewpoints
<a href="#">BLAZE 660A (Hexagon)</a>	Stereovision	Dimensional quality	Viewpoints
<a href="#">RoboticScan (Artec3D)</a>	Stereovision	Dimensional quality	Viewpoints
<a href="#">ATOS 5 (GOM)</a>	Stereovision	Dimensional quality	Viewpoints
<a href="#">ATOS TRIPLE SCAN (GOM)</a>	Stereovision	Dimensional quality	Viewpoints
<a href="#">Gocator (LMI Technologies)</a>	Stereovision	Circuit board inspection	Viewpoints
<a href="#">ARIS (ARIS)</a>	Laser	Dimensional quality	Viewpoints
<a href="#">Dimensional Gauging Perceptron (Perceptron),</a>	Laser	Dimensional quality	Viewpoints
<a href="#">Laser Radar MV331/351 (Nikon Metrology),</a>	Laser	Dimensional quality	Viewpoints
<a href="#">RAPID SCAN (API)</a>	Structured light	Dimensional quality	Viewpoints
<a href="#">COMET Pro AE (Zeis)</a>	Structured light	Dimensional quality	Viewpoints
<a href="#">FlexInspect (ABB),</a>	Structured light	Dimensional quality	Viewpoints
<a href="#">MetraScan3D (Creaform),</a>	Laser	Dimensional quality	Scanning
<a href="#">AirTrack (Kreon)</a>	Laser	Dimensional quality	Scanning
<a href="#">ABIS II (Zeis),</a>	Laser	Surface quality	Scanning

The proposed solutions for *partial measurements* are compatible with all technologies listed in the table above.

The proposed solutions for *coverage path planning and optimisation* as well as for *workpiece placement optimisation* are compatible with viewpoints-based technologies

The proposed solutions for *Root Cause Analysis* are compatible with all technologies that output high Dimensional Cloud of Point Data



# Thank-you

*Digital Lifecycle Management (DLM) Research Group*

*Please contact [Sumit Sinha](mailto:sumit.sinha.1@warwick.ac.uk) (email: [sumit.sinha.1@warwick.ac.uk](mailto:sumit.sinha.1@warwick.ac.uk)) in case of any doubts or collaboration*

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